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II. PARTIALLY OBSERVABLE MARKOV DECISION PROCESSES Formally, a partially observable Markov decision process is defined as a tuple $(S; A; T; R; O; Z; ; b_0)$ where S is a set of states with $s \in S$; A is a set of actions with $a \in A$; T defines a transition probability $P(s' | s, a, t)$; R defines the expected PROC IEEE, VOL. 101, NO. 5, 1160-1179, 2013 1 POMDP-based ... Manuscript received June 11, 2013; revised October 18, 2013; accepted October 20, 2013. Date of publication November 05, 2013; date of current version December 02, 2013. This work was supported in part by Spain MICIIN under projects CONSOLIDER CSD2008-00066

and METATRANSFER TEC2010-17512, and by AGAUR (Generalitat de Catalunya) through the 4090 IEEE TRANSACTIONS ON MICROWAVE THEORY AND TECHNIQUES ... Open Access Papers. The Computer Vision Foundation (CVF), one of our two overall meeting sponsors, has made preprint versions of CVPR 2013 papers available online. The Complete CVPR13 Pocket Guide is now available. Please also see the one page At-a-Glance Summary. CVPR 2013 Webpage - PAMITC June 2013 IEEE GEOSCIENCE AND REMOTE SENSING MAGAZINE 7 and spectral resolution instruments (see [3] and refer-ences therein). Figure 1 gives a partial account of the relevance of hyperspectral applications, by comparing paper counts

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